

Q2 (a) Determine whether the following signals are periodic or not of periodic then find its fundamental period

(i) $x(n) = (-1)^{n^2}$

(ii) $x(t) = \sum_{k=-\infty}^{\infty} (-1)^k \delta(t - 2k)$

Answer

(i) $x(n) = (-1)^{n^2}$

For given signal to be periodic

$$x(n + N) = x(n)$$

$$\therefore x(n + N) = (-1)(n + N)^2$$

$$= (-1)^{n^2} + N^2 + 2nN$$

$$= (-1)^{n^2} (-1)^{N^2} + 2nN$$

$$= x(n)(-1)^{N^2} + 2nN \dots \dots \dots (1)$$

$\therefore x(n)$ is periodic if

$$(-1)^{N^2} + 2nN = 1 = (-1)^{2m}$$

for $N = 1$ $(-1)^{1+2n} = -1 \neq 1$

for $N = 2$ $(-1)^{N^2+2nN} = (-1)^{4+4n} = 1$

\therefore Fundamental period of $x(n)$ is $N = 2$

(ii) $x(t) = \sum_{k=-\infty}^{\infty} (-1)^k \delta(t - 2k)$

For $x(t)$ to be periodic $x(t+T)=x(t)$

$$\therefore x(t+T) = \sum_{k=-\infty}^{\infty} (-1)^k \delta(t+T-2k)$$

Performing a change of variables

$$T - 2T = -2m$$

$$\frac{T}{2} - K = -m$$

$$K = \frac{T}{2} + m$$

$$x(t + T) = \sum_{k=-\infty}^{\infty} (-1)^{\frac{T}{2} + m} \delta(t - 2m)$$

$$= \sum_{k=-\infty}^{\infty} (-1)^m \delta(t - 2m) (-1)^{\frac{T}{2}}$$

$$= x(t) (-1)^{\frac{T}{2}}$$

for $x(t)$ to be periodic

$$(-1)^{\frac{T}{2}} = 1 = (-1)^{2m}$$

$$\frac{T}{2} = 2m$$

$$T = 4m$$

\therefore fundamental period of $x(t) = 4$

Q2 (b) For each of the following systems determine whether it is Memoryless, Causal, Stable, Linear and Time invariant.

(i) $y(n) = \log_e[x(n)]$

(ii) $y(n) = x(n^2)$

Answer

(i) $y(n) = \log_e[x(n)]$

As the present output depends on the present input only \therefore system is memory less, causal

- Assuming that input signal $x(n)$ satisfies the condition $|x(n)| \leq B_x < \infty$ for all n .

We can then find that

$$|y(x)| = |\log_e[x(n)]|$$

$$= |\log_e[Bx]| = By < \infty$$

\therefore for bounded i/p, system is giving a bounded o/p. Thus system is stable

- consider two arbitrary inputs $x_1(n)$ & $x_2(n)$

$$\begin{aligned}
 & | x_1(n) \leftrightarrow y_1(n) = \log_e[x_1(n)] \\
 & = x_2(n) \leftrightarrow y_2(n) = \log_e[x_2(n)] \\
 & = \text{let } x_3(n) = ax_1(n) + bx_2(n) \\
 & \text{for system to be linear} \\
 & y_3(n) = \log_e[x_3(n)] = \log_e[ax_1(n) + bx_2(n)] \\
 & \neq ay_1(n) + by_2(n) \\
 & \therefore \text{System is Non - Linear} \\
 & y_1(x) = \log_e[x_1(n)] \\
 & \text{shifted i/p } x_2(n) = x_1(n - n_0) \\
 & \text{O/p } y_2(n) = \log_e[x_2(n)] \\
 & = \log_e[x_1(n - n_0)] \\
 & \text{Now } y_1(n - n_0) = \log_e[x_1(n - n_0)] \\
 & \text{since } y_2(n) = y_1(n - n_0) \\
 & \therefore \text{system is Time - Invariant}
 \end{aligned}$$

(ii) $y(n) = x(n^2)$

- System has memory since the value of output signal $y(x)$ at time n depends on the future inputs

$$y(n)/n = n_0 = y(n_0) = x/n_0^2)$$

\therefore It is not memory less

- For bounded i/p system gives a bounded o/p \therefore System is BIBO stable.
- system is Non-Causal since present value of o/p $y(n)$ depends on the future values of input signal $x(n)$
- Consider two arbitrary inputs $x_1(n) \leftrightarrow y_1(n) = x_1(n^2)$

$$x_2(n) \leftrightarrow y_2(n) = x_2(n^2)$$

Let $x_3(n) = ax_1(n) + bx_2(n)$

If system is linear them

$$y_3(n) = ay_1(n) + by_2(n)$$

$$LHS \implies y_3(n) = x_3(n^2) = ax_1(n^2) + bx_2(n^2)$$

$$= ay_1(n) + by_2(n) = RHS$$

Since $LHS = RHS \therefore$ System is linear

$$* y_1(n) = x_1(n^2) = ax_1(n^2) + bx_2(n^2)$$

$$= ay_1(n) + by_2(n) = RHS$$

Since $LHS = RHS \therefore$ system is linear

$$* y_1(n) = x_1(n^2)$$

consider the shifted i/p $x_2(n) = x_1(n - n_0)$ o/p corresponding to shifted i/p $y_2(n) = x_2(n^2)$

$$y_2(n) = x_1(n^2 - n_0)$$

$$Now y_1(n - n_0) = x_1((n - n_0)^2)$$

$$\therefore y_2(n) \neq y_1(n - n_0)$$

\therefore system is Time - Variant

Q3 (a) Find the trigonometric Fourier series for the triangular wave shown in Fig.1 and hence plot its line spectrum.

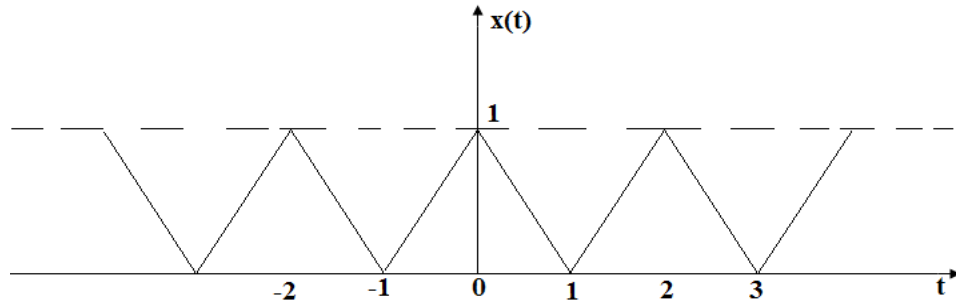


Fig.1

Answer

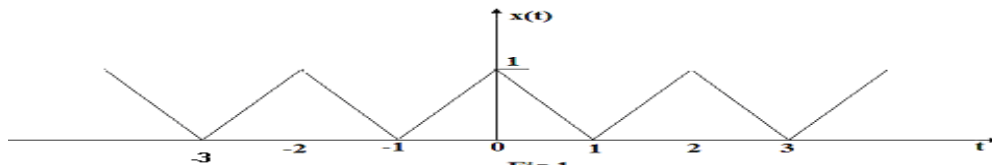


Fig.1

Waveform is periodic write period $T=2$

& Fundamental Frequency $w_0 = \frac{2\pi}{T}$

$$x(t) = \begin{cases} 1-t & 0 < t < 1 \\ t-1 & 1 < t < 2 \end{cases}$$

The Wave is an even function $\therefore b_n = 0$

$$a_0 = \frac{2}{T} \int_0^{T/2} x(t) dt = \frac{2}{2} \int_0^1 (1-t) dt$$

$$\Rightarrow \left| t - \frac{t^2}{2} \right|_0^1 = \frac{1}{2}$$

$$= a_n = \frac{4}{T} \int_0^{T/2} x(t) \cos(nw_0 t) dt$$

$$= \frac{4}{2} \int_0^1 (1-t) \cos(n\pi t) dt$$

$$= 2 \left[(1-t) \sin \frac{n\pi t}{n\pi} \Big|_0^1 - \left| \frac{\cos n\pi t}{n^2 \pi^2} \right|_0^1 \right]$$

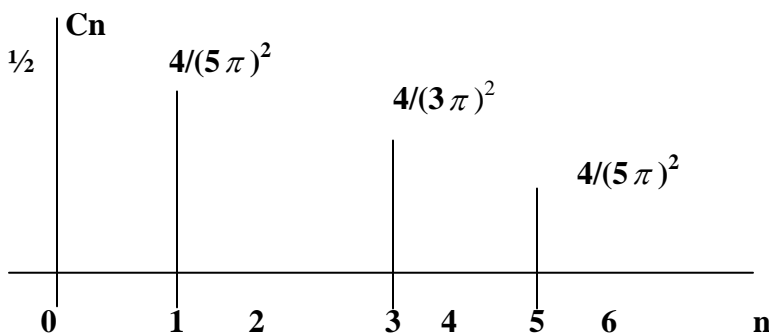
$$= \frac{2}{n^2 \pi^2} [1 - \cos(n\pi)]$$

$$a_n = \begin{cases} \frac{4}{n^2 \pi^2} & n = 1, 3, 5, \dots \\ 0 & n = 2, 4, 6, \dots \end{cases}$$

$$\therefore x(t) = a_0 + \sum_{n=1}^{\infty} a_n \cos(nw_0 t)$$

$$= \frac{1}{2} + \frac{4}{\pi^2} \cos(\pi t) + \frac{4}{(3\pi)^2} \cos(3\pi t) + \frac{4}{(5\pi)^2} \cos(5\pi t) + \dots$$

$$\text{line spectrum } c_n = \sqrt{a_n^2 + b_n^2} = |a_n|$$



Q3 (b) A continuous time periodic signal is real valued and has a fundamental period $T = 8$. The non zero Fourier series coefficients for $x(t)$ are $X_1 = X_{-1} = 2$, $X_3 = X_{-3}^* = 4j$. Express $x(t)$ in the form

$$x(t) = \sum_{n=0}^{\infty} A_n \cos(\omega_n t + \Phi_n)$$

Answer

Given:

$$T = 8 \therefore \omega_0 = \frac{2\pi}{8} = \frac{\pi}{4}$$

$$\text{we have } x(t) = \sum_{n=-\infty}^{\infty} X_n e^{-jn\omega_0 t} + X_{-3} e^{-j3\omega_0 t}$$

$$= 2e^{j\frac{\pi}{4}t} + 2e^{-j\frac{\pi}{4}t} + 4je^{j3\pi/4t} - 4je^{-j3\pi/4t}$$

$$= 4\cos\left(\frac{\pi}{4}t\right) - 8\sin\left(\frac{3\pi}{4}t\right)$$

$$x(t) = 4\cos\left(\frac{\pi}{4}t\right) + 8\cos\left(\frac{3\pi}{4}t + \frac{\pi}{2}\right)$$

Q3 (c) Find the time domain signal corresponding to following DTFS coefficients

Answer

$$X_k = \cos\left(\frac{k4\pi}{11}\right) + 2j\sin\left(\frac{k6\pi}{11}\right)$$

$$= \frac{1}{2}e^{j4\frac{\pi}{11}k} + \frac{1}{2}e^{-j4\frac{\pi}{11}k} + e^{j6\frac{\pi}{11}k} - e^{-j6\frac{\pi}{11}k}$$

$$= \frac{1}{2}e^{j2\frac{\pi}{11}2k} + \frac{1}{2}e^{-j2\frac{\pi}{11}2k} e^{j2\frac{\pi}{11}11k} + e^{j2\frac{\pi}{11}3k} - e^{j2\frac{\pi}{11}11k}$$

$$= \frac{1}{2}e^{j2\frac{\pi}{11}2k} + \frac{1}{2}e^{j2\frac{\pi}{11}9k} + e^{j2\frac{\pi}{11}3k} - e^{j2\frac{\pi}{11}8k}$$

$$= \frac{1}{11} \sum_{k=0}^{10} \left[\frac{11}{2} \delta(n-2) + 11\delta(n-3) - 11\delta(n-8) + \frac{11}{2} \delta(n-1) \right] e^{j2\frac{\pi}{11}nk}$$

$$X_k = \frac{11}{N} \sum_{k=0}^{N-1} x(n) e^{j2\frac{\pi}{N}nk}$$

Comparing the above two equations

$$= x(n) = \frac{11}{2} \delta(n-2) + 11\delta(n-3) - 11\delta(n-8) + \frac{11}{2} \delta(n-9)$$

Q4 (a) State and Prove duality property of Continuous Time Fourier Transform. Using it, find the Fourier Transform of following signals

(i) $g(t) = \frac{1}{1+jt}$

(ii) $x(t) = \frac{1}{1+t^2}$

Answer

Duality property of $x(t) \leftrightarrow X(\omega)$

then $x(t) \leftrightarrow 2\pi X(-\omega)$

proof : - $x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega$

$$2\pi x(t) = \int_{-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega$$

Replace t by -t

$$2\pi x(-t) = \int_{-\infty}^{\infty} X(\omega) e^{-j\omega t} d\omega$$

Interchanging the variables t and ω .

$$2\pi x(-\omega) = \int_{-\infty}^{\infty} X(t) e^{-j\omega t} dt$$

$$2\pi x(-\omega) = F[X(t)]$$

$$x(t) \leftrightarrow 2\pi x(-\omega)$$

(i) $g(t) = \frac{1}{1+jt}$

Define $x(\omega) = \frac{1}{1+j\omega}$ & replace t with ω in the expression of g(t)

$$e^{-at} u(t) \leftrightarrow \frac{1}{a+j\omega}$$

Substituting a = 1

$$e^{-t} u(t) \leftrightarrow \frac{1}{1+j\omega}$$

$$x(t) = e^{-t} u(t) \quad \& \quad x(\omega) = \frac{1}{1+j\omega}$$

$$x(-\omega) = e^{\omega} u(-\omega) \quad \& \quad x(t) = \frac{1}{1+jt}$$

According to duality

$$x(t) \leftrightarrow 2\pi x(-\omega)$$

$$\frac{1}{1+jt} \leftrightarrow 2\pi e^{\omega} u(-\omega)$$

$$f\left[\frac{1}{1+jt}\right] = 2\pi e^{\omega} u(-\omega)$$

$$(ii) \quad x(t) = \frac{1}{1+t^2}$$

$$\text{we have, } e^{-a|t|} \leftrightarrow \frac{2a}{a^2 + \omega^2}$$

$$\text{Put } a = 1 \quad e^{-a|t|} \leftrightarrow \frac{2}{1 + \omega^2}$$

$$\frac{1}{2} e^{-a|t|} \leftrightarrow \frac{1}{1 + \omega^2}$$

$$x(t) = \frac{1}{2} e^{-a|t|} \quad \text{and } x(\omega) = \frac{1}{1 + \omega^2}$$

$$x(-\omega) = \frac{1}{2} e^{-|\omega|} \quad x(t) = \frac{1}{1+t^2}$$

$$= \frac{1}{2} e^{-|\omega|}$$

Acc.to Duality

$$X(t) \leftrightarrow 2\pi x(-\omega)$$

$$= \frac{1}{1+t^2} \leftrightarrow 2\pi \cdot \frac{1}{2} e^{-|\omega|}$$

$$= \frac{1}{1+t^2} \leftrightarrow \pi e^{-|\omega|}$$

$$= F\left[\frac{1}{1+t^2}\right] = \pi e^{-|\omega|}$$

Q4 (b) Consider a stable LTI system characterized by the differential equation

$$\frac{d^2 y(t)}{dt^2} + 4 \frac{dy(t)}{dt} + 3y(t) = \frac{dx(t)}{dt} + 2x(t)$$

(i) Find the frequency response $H(\omega)$ and impulse response $h(t)$ of the system.

(ii) What is the response of this system if the input $x(t) = e^{-t}u(t)$

Answer

$$\frac{d^2 y(t)}{dt^2} + 4 \frac{dy(t)}{dt} + 3y(t) = \frac{dx(t)}{dt} + 2x(t)$$

Taking Fourier Transform on both sides

$$(j\omega)^2 y(\omega) + 4j\omega y(\omega) + 3y(\omega) = j\omega x(\omega) + 2x(\omega)$$

$$H(\omega) = \frac{y(\omega)}{x(\omega)} = \frac{2 + j\omega}{(j\omega)^2 + 4j\omega + 3} = \frac{2 + j\omega}{(1 + j\omega)(3 + j\omega)}$$

$$H(\omega) = \frac{1}{2} \cdot \frac{1}{1 + j\omega} + \frac{1}{2} \cdot \frac{1}{3 + j\omega}$$

Taking inverse Fourier Transform

$$h(t) = \frac{1}{2} e^{-t} u(t) + \frac{1}{2} e^{-3t} u(t)$$

(ii) Given $x(t) = e^{-t} u(t)$

$$x(\omega) = \frac{1}{1 + j\omega}$$

$$y(\omega) = x(\omega) \cdot H(\omega) = \left[\frac{1}{1 + j\omega} \right] \left[\frac{2 + j\omega}{(1 + j\omega)(3 + j\omega)} \right]$$

$$\Rightarrow \frac{2 + j\omega}{(1 + j\omega)^2 (3 + j\omega)}$$

$$y(\omega) = \frac{1}{4} \frac{1}{1 + j\omega} + \frac{1}{2} \frac{1}{(1 + j\omega)^2} - \frac{1}{4} \frac{1}{3 + j\omega}$$

Taking inverse Fourier Transform

$$y(t) = \left[\frac{1}{4} e^{-t} + \frac{1}{2} t e^{-t} - \frac{1}{4} e^{-3t} \right] u(t)$$

Q5 (a) Suppose that a system has the response $\left(\frac{1}{4}\right)^n u(n)$ to the input

$(n+2)\left(\frac{1}{2}\right)^n u(n)$. If the output of this system is $\delta(n) - \left(-\frac{1}{2}\right)^n u(n)$, what

is the input?

Answer

$$\begin{aligned} \text{Given that } x(n) &= (n+3)\left(\frac{1}{2}\right)^n u(n) \\ &= n\left(\frac{1}{2}\right)^n u(n) + 2\left(\frac{1}{2}\right)^n u(n) \end{aligned}$$

Taking DTFT of the above equation

$$\begin{aligned} x(e^{j\omega}) &= \frac{\frac{1}{2}e^{-j\omega}}{\left(1 - \frac{1}{2}e^{-j\omega}\right)^2} + 2\frac{1}{1 - \frac{1}{2}e^{-j\omega}} \\ &= \frac{2\left(1 - \frac{1}{4}e^{-j\omega}\right)}{\left(1 - \frac{1}{2}e^{-j\omega}\right)^2} \end{aligned}$$

$$\text{Given } y(n) = \left(\frac{1}{4}\right)^n u(n)$$

$$y(e^{j\omega}) = \frac{1}{1 - \frac{1}{4}e^{-j\omega}}$$

$$H(e^{j\omega}) = \frac{y(e^{j\omega})}{x(e^{j\omega})} = \frac{\left(1 - \frac{1}{2}e^{-j\omega}\right)^2}{2\left(1 - \frac{1}{4}e^{-j\omega}\right)}$$

$$\text{Given } y(x) = \delta(n) - \left(-\frac{1}{2}\right)^n u(n)$$

$$y(e^{j\omega}) = 1 - \frac{1}{1 + \frac{1}{2}e^{-j\omega}} = \frac{\frac{1}{2}e^{-j\omega}}{1 + \frac{1}{2}e^{-j\omega}}$$

$$\begin{aligned}
 x(e^{j\omega}) &= \frac{2\left(1 - \frac{1}{4}e^{-j\omega}\right)^2}{\left(1 - \frac{1}{2}e^{-j\omega}\right)^2} = y(e^{j\omega}) \\
 &= \frac{2\left(1 - \frac{1}{4}e^{-j\omega}\right)}{\left(1 - \frac{1}{2}e^{-j\omega}\right)^2} = \frac{\frac{1}{2}e^{-j\omega}}{1 + \frac{1}{2}e^{-j\omega}} \\
 &= \frac{e^{-j\omega}\left(1 - \frac{1}{4}e^{-j\omega}\right)^2}{\left(1 - \frac{1}{2}e^{-j\omega}\right)^2\left(1 + \frac{1}{2}e^{-j\omega}\right)} \\
 &= \frac{\frac{3}{8}e^{-j\omega}}{1 + \frac{1}{2}e^{-j\omega}} + \frac{\frac{3}{8}e^{-j\omega}}{1 - \frac{1}{2}e^{-j\omega}} + \frac{\frac{1}{8}e^{-j\omega}}{\left(1 - \frac{1}{2}e^{-j\omega}\right)^2}
 \end{aligned}$$

Taking inverse DTFT

$$x(n) = \frac{3}{8}\left(-\frac{1}{2}\right)^{n-1} u(n-1) + \frac{3}{8}\left(\frac{1}{2}\right)^{n-1} u(n-1) + \frac{1}{4}n\left(\frac{1}{2}\right)^n u(n)$$

Q5 (b) State and Prove convolution property of Discrete Time Fourier Transform. Using it determine the convolution $x(n) = x_1(n) * x_2(n)$ of the sequences, where

$$x_1(n) = x_2(n) = \delta(n+1) + \delta(n) + \delta(n-1)$$

Answer

Convolution property:

If

$$x_1(n) \leftrightarrow x_1(e^{j\omega}) \quad x_2(n) \leftrightarrow x_2(e^{j\omega})$$

$$\text{then } x_1(n) + x_2(n) \leftrightarrow x_1(e^{j\omega}) x_2(e^{j\omega})$$

$$\text{proof : - } f[x_1(n) + x_2(n)] = \sum_{n=-\infty}^{\infty} [x_1(n) + x_2(n)] e^{-j\omega n}$$

$$= \sum_{n=-\infty}^{\infty} \left(\sum_{m=-\infty}^{\infty} x_1(m) x_2(n-m) \right) e^{-j\omega n}$$

Interchanging the order of summation

$$= \sum_{m=-\infty}^{\infty} x_1(m) \left(\sum_{n=-\infty}^{\infty} x_2(n-m) e^{-j\omega n} \right)$$

Apply time shifting property to the bracketed term

$$= x_2(e^{j\omega}) x_1(e^{j\omega}) = x_1(e^{j\omega}) x_2(e^{j\omega})$$

$$= x_1(n) \times x_2(n) \leftrightarrow x_1(e^{j\omega}) x_2(e^{j\omega})$$

$$x_1(n) = x_2(n) = \{ \uparrow \} = \delta(n+1) + \delta(n) + \delta(n-1)$$

$$x_1(e^{j\omega}) = x_2(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x_1(n) e^{-j\omega n}$$

$$= \sum_{n=-1}^1 e^{-j\omega n}$$

$$= e^{j\omega} + 1 + e^{-j\omega}$$

$$= 1 + 2 \cos \omega$$

Using condition property,

$$F[x_1(n) + x_2(n)] = x_1(e^{j\omega}) \cdot x_2(e^{j\omega})$$

$$= [1 + 2 \cos \omega]^2$$

$$= 3 + 4 \cos \omega + 2 \cos(2\omega)$$

$$= 3 + 2(e^{j\omega} + e^{-j\omega}) + (e^{j2\omega} + e^{-j2\omega})$$

$$= e^{j2\omega} + 2e^{j\omega} + 3 + 2e^{-j\omega} + e^{-j2\omega}$$

$$= x(n) = \delta(n+2) + 2\delta(n+1) + 3\delta(n) + 2\delta(n-1) + \delta(n-2)$$

$$= \{1, 2, 3, 2, 1\}$$

Q6 (a) Determine the conditions on the sampling interval T_s so that each $x(t)$ is uniquely represented by the discrete time sequence $x(n) = x(nT_s)$.

(i) $x(t) = \cos(\pi t) + 3 \sin(2\pi t) + \sin(4\pi t)$

(ii) $x(t) = \cos(2\pi t) \sin c(t) + 3 \sin(6\pi t) \sin c(2t)$

Answer

$$x(t) = \cos(\pi t) + 3 \sin(2\pi t) + \sin(4\pi t)$$

Comparing it with

$$x(t) = A_1 \cos(w_1 t) + A_2 \sin(w_2 t) + A_3 \sin(w_3 t)$$

$$w_1 = \pi, w_2 = 2\pi, w_3 = 4\pi$$

$$W_{\max} = w_3 = 4\pi \quad \text{or} \quad f_{\max} = \frac{W_{\max}}{2\pi} = 2$$

$$\therefore \text{Sampling frequency } w_s \geq 2w_{\max} = 8\pi \text{ rad/sec}$$

$$\text{or } f_s \geq 2f_{\max} = 4\text{Hz}$$

$$\text{Hence sampling interval } T_s \leq \frac{1}{4}$$

(ii) Given $x(t) = \cos(2\pi t) \sin c(t) + 3 \sin(6\pi t) \sin c(2t)$

$$= \cos(2\pi t) \frac{\sin(\pi - t)}{\pi} + 3 \sin(6\pi t) \frac{\sin(2\pi t)}{2\pi}$$

$$= \frac{1}{(2\pi)} [\sin(3\pi t) - \sin(\pi t)] + 3 \sin(6\pi t) \frac{\sin(2\pi t)}{2\pi}$$

$$= \frac{1}{2\pi} [\sin(3\pi t) - \sin(\pi t)] + \frac{3}{4\pi} [\cos(4\pi t) - \cos(8\pi t)]$$

$$\text{Maximum freq. is } w_{\max} = 8\pi \quad \text{or} \quad f_{\max} = \frac{w_{\max}}{2\pi} = 4$$

$$\text{Sampling freq. } f_s \geq 2f_{\max} = 8\text{Hz}$$

$$\text{Sampling Interval } T_s \leq \frac{1}{8}$$

Q6 (b) A causal LTI system is described by the differential equation

$$\frac{dy(t)}{dt} + 2y(t) = x(t)$$

Determine:

- (i) The frequency response of the system
- (ii) The group delay associated with the system
- (iii) Output of the system to the input $x(t) = e^{-t}u(t)$
- (iv) Output of the system if the input has its fourier transform

$$X(j\omega) = \frac{j\omega + 1}{(j\omega + 2)}$$

Answer

- (i) Taking F.transform both the sides of given equ

$$j\omega y(\omega) + 2y(j\omega) = x(j\omega)$$

$$H(j\omega) = \frac{y(j\omega)}{x(j\omega)} = \frac{1}{j\omega + 2}$$

$$(ii) \quad \angle H(j\omega) = -\tan^{-1}\left(\frac{\omega}{2}\right)$$

$$T(\omega) = -\frac{d}{d\omega} \{\angle H(j\omega)\} = -\frac{d}{d\omega} \left\{ -\tan^{-1}\left(\frac{\omega}{2}\right) \right\}$$

$$= \frac{1}{1 + \left(\frac{\omega}{2}\right)^2} \cdot \frac{1}{2} = \frac{2}{4 + \omega^2}$$

$$(iii) \quad x(t) = e^{-t}u(t)$$

$$x(j\omega) = \frac{1}{j\omega + 1}$$

$$y(j\omega) = H(j\omega) \times (j\omega) = \frac{1}{(j\omega + 1)(j\omega + 2)}$$

$$= \frac{1}{(j\omega + 1)} - \frac{1}{(j\omega + 2)}$$

Taking inverse fouries transform

$$y(t) = [e^{-t} - e^{-2t}]u(t)$$

$$(iv) H(j\omega).X(j\omega) = \frac{j\omega + 1}{(j\omega + 2)^2}$$

Taking inverse fouries transform

$$y(t) = [e^{-2t} - te^{-2t}]u(t)$$

Q7 (a) Consider the signal $x(t) = e^{-5t}u(t-1)$ and its Laplace Transform be $X(s)$

- (i) Evaluate $X(s)$ and find its ROC
- (ii) Determine the values of the finite numbers A and t_0 such that the Laplace transform $G(s)$ of $g(t) = Ae^{-5t}u(-t-t_0)$ has the same algebraic form as $X(s)$. What is the ROC corresponding to $G(s)$?

Answer

- (i) By definition

$$x(s) = \int_{-\infty}^{\infty} x(t)e^{-st} dt$$

$$x(s) = \int_{-\infty}^{\infty} e^{-st} u(t-1) e^{-st} dt$$

$$u(t-1) = \begin{cases} 1 & t > 1 \\ 0 & t < 1 \end{cases}$$

$$\begin{aligned} x(s) &= \int_1^{\infty} e^{-st} e^{-st} dt = \int_1^{\infty} e^{-1(5+5)t} dt \\ &= \left[\frac{e^{-(5+5)t}}{-(5+5)} \right]_1^{\infty} = -(s+5) [0 - e^{-(5+5)t}] \\ &= \frac{e^{-(5+5)t}}{s+5} \quad \text{R.O.C } \{s\} > -5 \end{aligned}$$

(ii)

$$G(s) = \int_{-\infty}^{\infty} g(t)e^{-st} dt$$

$$= \int_{-\infty}^{\infty} A e^{-5t} u(-t - t_0) e^{-st} dt$$

$$u(-t - t_0) = \begin{cases} 1 & (-t - t_0) > 0 \rightarrow t < -t_0 \\ 0 & (-t - t_0) < 0 \rightarrow t > -t_0 \end{cases}$$

$$G(s) = \int_{-\infty}^{-t_0} A e^{-5t} e^{-st} dt = \int_{-\infty}^{-t_0} A e^{-(s+5)t} dt$$

$$= A \left[\frac{-A e^{(s+5)t_0}}{s+5} \right]_{-\infty}^{-t_0}$$

$$G(s) = \frac{-A e^{(s+5)t_0}}{s+5} \dots \dots \dots G(s) = x(s) \text{ if}$$

$$A = -1, t_0 = -1.$$

R.O.C

$$\text{R}\{s\} < -5$$

Q7 (b) Find the inverse Laplace transform of $X(s) = \frac{-3}{(s+2)(s-1)}$

If the ROC is:

- (i) $\text{Re}\{s\} > 1$
- (ii) $\text{Re}\{s\} < -2$
- (iii) $-2 < \text{Re}\{s\} < 1$

Answer

$$X(s) = \frac{-3}{(s+2)(s-1)}$$

$$= \frac{1}{s+1} - \frac{1}{s-1}$$

$X(s)$ has poles at -2 and 1

(i)

$$ROCR\{s\} > 1$$

Is to the right of the rightmost poles so both poles correspond to casual signals.

\therefore

$$e^{-2t}u(t) \leftrightarrow \frac{1}{s+2}$$

$$e^t u(t) \leftrightarrow \frac{1}{s-1}$$

and

$$x(t) = e^{-2t}u(t) - e^t u(t)$$

(ii)

$R(s) < -2$ is to the left of leftmost pole so both poles correspond to anticausal signals \therefore

$$-e^{-2t}u(t) \leftrightarrow \frac{1}{s+2}$$

$$-e^{-t}u(t) \leftrightarrow \frac{1}{s-1}$$

and

$$x(t) = -e^{-2t}u(-t) + e^t u(t)$$

$$(iii) -2 < R\{s\} < 1$$

for pole at -2 ROC lies to the right of this pole \therefore . This pole corresponds to a casual signal.

$$\therefore e^{-2t}u(t) \leftrightarrow \frac{1}{s+1}$$

Second pole is at $s=1$. Hence ROC is to the left of this pole. So this pole corresponds to the anticausal

$$\therefore -e^t u(-t) \leftrightarrow \frac{1}{s-1}$$

Hence

$$x(t) = e^{-2t}u(t) + e^t u(-t)$$

Q8 (a) Determine the signal $x(n]$ whose z-transform is given by $X(z) = \log(1 + az^{-1}), |z| > |a|$

Answer

$$X(z) = \log(1 + az^{-1}), |z| > |a|$$

$$\frac{dx(z)}{dz} = \frac{-az^{-2}}{1 + az^{-1}}$$

$$-Z\left(\frac{dx(z)}{dz}\right) = \frac{-az - 1}{1 + az - 1}$$

Take inverse Z-transform

$$(z^{-1}) = \left[- = \frac{dx(z)}{dz} \right] = z^{-1} \left[\frac{-az - 1}{1 + az - 1} \right]$$

$$nx(n) = z^{-1} \left[\frac{-az^{-1}}{1 + az^{-1}} \right]$$

we know

$$a^n u(n) \leftrightarrow \frac{1}{1 - az^{-1}}$$

$$(-a)^n u(n) \leftrightarrow \frac{1}{1 + az^{-1}}$$

$$|Z| > |a|$$

$$a(-a)^n u(n) \leftrightarrow \frac{a}{1 + az^{-1}} \quad |z| > |a|$$

Using time-shifting property,

$$a(-a)^{n-1} u(n-1) \leftrightarrow \frac{az^{-1}}{1 + az^{-1}} \quad |z| > |a|$$

$$-(-a)^n u(n-1) \leftrightarrow \frac{az^{-1}}{1 + az^{-1}} \quad |z| > |a|$$

consequently

$$nx(n) = -(-a)^n u(n-1)$$

$$x(n) = \frac{-(-a)^n}{n} u(n-1) = \frac{1}{n} (-1)^{n+1} a^n u(n-1)$$

Q8 (b) Find the inverse z-transform of $X(z) = \frac{1+z^{-1}}{1-(1/3)z^{-1}}$

When,

- (i) ROC: $|z| > 1/3$
- (ii) ROC : $|z| < 1/3$, using power series expansion

Answer

$$\begin{array}{r}
 1 + \frac{4}{3}z^{-1} + \frac{4}{9}z^{-2} + \frac{4}{27}z^{-3} + \dots \\
 \hline
 1 - 1/3z^{-1} \Big) 1 + z^{-1} \\
 \underline{1 - \frac{1}{3z^{-1}}} \\
 \frac{4}{3}z^{-1} - \frac{4}{9}z^{-2} \\
 \underline{\frac{4}{9}z^{-2}} \\
 \frac{4}{9}z^{-2} - \frac{4}{27}z^{-3} \\
 \underline{\frac{4}{27}z^{-3}} \\
 \dots
 \end{array}$$

$$\therefore x(z) = 1 + \frac{4}{3}z^{-1} + \frac{4}{9}z^{-2} + \frac{4}{27}z^{-3} \dots$$

$$\therefore x(n) = \left\{ 0, \frac{4}{3}, \frac{4}{9}, \frac{4}{27}, \dots \right\}$$

(ii)

$$\begin{array}{r}
 -\frac{1}{3}z^{-1} + 1 \Big) \frac{-3 - 12z - 36z^2 + \dots}{z^{-1} - 3} \\
 \underline{-z^{-1} + 3} \\
 4 \\
 \underline{4 - 12z} \\
 12z \\
 \underline{12z - 36z^2} \\
 36z^2 \\
 \dots
 \end{array}$$

Q9 (a) A random variable X has the uniform distribution given by

$$f_X(x) = \begin{cases} \frac{1}{2\pi}, & \text{for } 0 \leq x \leq 2\pi \\ 0, & \text{otherwise} \end{cases}$$

Determine its mean and variance

Answer

$$m_x = \int_{-\infty}^{\infty} x f_X(x) dx = \int_0^{2\pi} x \cdot \frac{1}{2\pi} dx$$

$$= \frac{1}{2\pi} \int_0^{2\pi} x dx = \frac{1}{2\pi} \left[\frac{x^2}{2} \right]_0^{2\pi} = \pi$$

$$E[x^2] = \int_{-\infty}^{\infty} x^2 f_X(x) dx = \int_0^{2\pi} x^2 \cdot \frac{1}{2\pi} dx$$

$$= \frac{1}{2\pi} \int_0^{2\pi} x^2 dx = \frac{1}{2\pi} \left[\frac{x^3}{3} \right]_0^{2\pi} = \frac{4}{3} \pi^2$$

$$\text{variance } x^2 = E[x^2] - [E[x]]^2$$

$$= \frac{4}{3} \pi^2 - \pi^2 = \frac{\pi^2}{3}$$

Q9 (b) A WSS random process X(t) with autocorrelation function $R_X(\tau) = e^{-a|\tau|}$ where a is a real positive constant is applied to the input of LTI system with impulse response $h(t) = e^{-bt} u(t)$ where b is real positive constant. Find the autocorrelation function of the output Y(t) of the system.

Answer

Frequency response H/W of the system

$$H(\omega) = F[h(t)] = \frac{1}{\omega + b}$$

Power spectral density of X(t) is

$$S_X(\omega) = F[R_X(z)] =$$

$$\frac{2}{\omega^2 + a^2}$$

$$s_r(\omega) = |H(\omega)|^2 S_X(\omega) = \left(\frac{1}{\omega^2 + b^2} \right) \left(\frac{2a}{\omega^2 + b^2} \right)$$

$$= \frac{a}{(a^2 - b^2)b} \left(\frac{2b}{\omega^2 + b^2} \right) - \frac{b}{(a^2 - b^2)b} \left(\frac{2a}{\omega^2 + a^2} \right)$$

Taking inverse Fourier transform on both sides

$$R_Y(c) = \frac{1}{(a^2 + b^2)b} [a e^{-b|c|} - b e^{-a|c|}]$$

Text Books

1. **Signals and Systems, A.V. Oppenheim and A.S. Willsky with S. H. Nawab, Second Edition, PHI Private limited, 2006.**
2. **Communication Systems, Simon Haykin, 4th Edition, Wiley Student Edition, 7th Reprint 2007.**