ROLL NO.	

Subject: COMPUTER GRAPHICS & VISUALIZATION Code: AC111/AT111

AMIETE - CS/IT {NEW SCHEME}

DECEMBER 2014 Time: 3 Hours Max. Marks: 100

PLEASE WRITE YOUR ROLL NO. AT THE SPACE PROVIDED ON EACH PAGE IMMEDIATELY AFTER RECEIVING THE QUESTION PAPER.

NOTE: There are 9 Questions in all.

- Question 1 is compulsory and carries 20 marks. Answer to Q.1 must be written in the space provided for it in the answer book supplied and nowhere else.
- The answer sheet for the Q.1 will be collected by the invigilator after 45 minutes of the commencement of the examination.

Q.1	Choose the correct or the bo	est alternative in the following:	$(2\times10$
a. Name the printer that also scans raster patterns from an inter- rapidly sweeping a laser beam over an internal drawing surface.		<u>*</u>	buffer,
	(A) Inkjet printer(C) Laser printer	(B) Dot matrix printer(D) All of these	
	b is to primitives.	sed to control the basic display properties	of output
	(A) attribute parameter(C) getpixel	(B) setpixel(D) putpixel	
	c. The technique of using increased visual resolution	a minimum number of intensity levels is called	to obtain
	(A) Dithering(C) Depth cueing	(B) Halftoning(D) Rendering	
	polygon, but instead of cli	rithm which performs clipping against pping a single line segment it clips an entire against the convex polygon and its output	e polygon
	(A) Cohen-Sutherland(B) Cyrus-Beck		
	(C) Weiler-Atherton		
	(D) Sutherland-Hodgman		

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e.	An important property assumed for diffuse scattering is that it is independent of the direction from the point, P, to the location of the viewer's eye. This is often called as				
	 (A) Lambert's law (B) Refraction (C) Omnidirectional scattering (D) Specular reflection 				
f. Transformation which compresses or expands the dimensions of an object.					
	(A) Translation(C) Rotation	(B) Scaling(D) Reflection			
g.	When an input device is placed is device operate simultaneously.	n, the program and			
	(A) Sample mode(C) Action mode	(B) Event mode(D) Choice mode			
h.	World coordinate system is somethin	ng in which			
	 (A) the image is defined (B) the object is defined (C) the surfaces are defined (D) the transformations are defined 				
i.	If we rotate the point $P = (3,1,4)$ thro	ough 300° about the Y-axis, then			
	 (A) the X-coordinate of the point is n (B) the Y-coordinate of the point is n (C) the Z-coordinate of the point is n (D) none of these 	not altered			
j.	Aliasing means				
	(A) Rendering effect(C) Staircase effect	(B) Shading effect(D) Cueng effect			
	Answer any FIVE Questions out of EIGHT Questions. Each question carries 16 marks.				
a.	Name some digital input devices an functioning.	d briefly explain them with respect to their (8)			

Q.2

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	b.	Compute the following:	(2×4)
		 (i) Size of 800 x 600 image at 240 pixels per inch. (ii) Resolution of 2 x 2 inch image that has 512 x 512 pixels. (iii) Height of the resized image 1024 x 768 to one that is 640 pixels the same aspect ratio. (iv) Width of an image having height of 5 inches and an aspect ratio 1.5 	
Q.3	a.	a. State and explain DDA algorithm for line drawing along with its drawbac	
	b.	Discuss the two primary ways to describe the shape of a curved line.	(8)
Q.4	a.	Explain the following functions related to Area-Fill attributes: (i) setInteriorColourIndex(fc) (ii) setInteriorStyleIndex(pi) (iii)setPatternSize(dx, dy) (iv)setPixel(x, y, cp(y mod ny + 1, x mod nx + 1)	(8)
	b.	Describe the different approaches to antialiasing techniques.	(8)
Q.5	a.	Explain the effects of 3D geometric transformations.	(8)
	b.	Perform a 45 [®] rotation of triangle A (0, 0), B (1, 1), C (5, 2) (i) about the origin (ii) about P(-1, -1)	(2×4)
Q.6	a.	Explain Sutherland-Hodgeman algorithm for polygon clipping. For whof clipping regions the algorithm is not suitable. Give reason.	nat type (8)
	b.	Use the Liang-Barsky line clipping algorithm to clip the line $P_1(-15, P_2(30, 60))$ against the window having diagonally opposite corners as $(0, 15, 15)$.	
Q.7	a.	Explain, why there is a need for visible surface detection? Diffe between object precision and image precision methods for detecting surface.	
	b.	Describe Depth Buffer hidden surface elimination method.	(8)
Q.8	a.	What are the various input mode functions that specify how the prograinput devices interact?	am and (8)
	b.	Describe the various techniques that can be incorporated into g packages to aid the interactive construction of pictures.	graphics (8)
Q.9	a.	What do you mean by computer-assisted animation? Differentiate	it with

(8)

(8)

manipulate a model.

computer-generated animation.

b. Describe the methods for specifying the information needed to construct and